



Pierre Lagarrigue, 2005

#### Getting started manual

#### Introduction

The aim of this tutorial is to explain students how to use the machining center and the CN lathe of the UPS's workshop.

#### **Exercise :**

We suppose that the measurement origin (called Om) is located at the intersection between the gauge plane of the cone of the spindle and the z axis. The part origin (called Op) is choosen on the machining assembly as shown below. The program origin will be defined later. The gauge used measures 199,34 mm long and the radius of the ball is 4,99 mm. Calculate vector  $\overline{O_{1}O_{2}}$  (called upster DATLin NUM language)

 $\overline{OmOp}$  (called vector DAT1 in NUM language)



# <u>Remenber</u>



**Partie 2 : Getting started** The tutorial is divided in 7 parts :

Switch the machine on

Manual movments :

Homing procedure (M.O.S.) :

**Door shut :** 

**Programmed movments** 

**Calculation of DAT1 :** 

Entering DAT1 values using the keyboard

## SWITCHING THE MACHINE ON



Clic on the contact button
Unlock the emergency stop
Clic on the 2 reset buttons
Turn the key to switch the hydraulic system on
If everything is OK, the « power » indicator lightens.

#### MANUAL MOVEMENTS



Select the MANUAL mode
For an unlimited movement, select the ILL mode
Turn the feed potentiometer to 100 %
Press on the button of the selected axis.
For an incrementl movement, choose the value of the displacement (10, 100, ou 1000 $\mu$ m ) then press on the button of the selected axis

### HOMING PROCEDURE (M.O.S.)



Select the MANUAL mode
Sélect the ILL mode
Turn the feed potentiometer to 100 %
Move on X-, Y- et Z- axes beyond the MOS point
Select the MOS mode
Press on the $Z+$ button. When the movements stops, the MOS point on Z axis is reached. Do the for the other axes. The « default » indicator switches off if the homing procedure has correctly be executed.
Press this button to reset the tool changer

# **CLOSED DOOR VALIDATION**



Select the IMD mode
The « default » and « stop » indicators lighten red
Shut the door
Turn the key
Press on "machining stop". The « default » and « stop » indicators switch off. The door is closed and the closure is validated.

# DÉPLACEMENTS EN MODE IMD



Select the IMD mode
Write a block : for example G0 G52 X0 Y0 Z0 B0 to reach the measurement origin. Press LF to validate
Turn the feed potentiometre to 0
Press on cycle start
Check with the deltas that the movments will be correct. Then turn up the feed potentiometer progressively.

# **CALCULATION OF DAT1**



Select the manual mode
Put feeler in the spindle. Set the machining assembly normal to the spindle (IMD mode, then strike G0 G52 B180, LF and CYCLE START ; Turn the potentiometer to 100 %)
Select the ILL mode and let the feeler go close to the surface under consideration
Select the incremental mode (0.1 mm) to touch the surafce under consideration beware : admitted range on X or Y axis : 0,5 mm ; on z axis : 10 mm.
Display the coordinates relatively to Om. Then calculate DAT1 on axis under consideration.

# ENTERING DAT1 VALUES USING THE KEYBOARD



	Select the DAT mode
	Strike ion the keyboard the new values of DAT 1 (For examle. : X-250 ; Y-200 ; Z-300 ; ) ; press LF to validate
	Using the manual mode, go back on Z axis
	Select the IMD mode. Ask for the displacement G1 X0 Y0 Z199.34.
?	Is the feeler gauge correctly positionnated ? Are the DAT1 correct ?, Why having programmated Z199.34 ?

# **INTRODUCTION DES DEC1 AU CLAVIER**



Sélectionner le mode PREF
Appuyer sur la touche "suite"
Entrer les valeurs du décalage